

Outline

- ▶ Day 1
 - ▶ Review
 - ▶ Math and Quantum Mechanics Review
 - ▶ Introduction to the Algorithm
 - ▶ Classical Search Algorithms
 - ▶ Visually Implement Grover's
- ▶ Day 2
 - ▶ Coding the Two Qubit Case
 - ▶ Coding the General Case (Three Ways)

Review

Statevectors Are Made of Basis States

- ▶ Consider the following state vector:

$$|\psi\rangle = \frac{1}{2}|00\rangle + \frac{1}{2}|01\rangle + \frac{1}{2}|10\rangle + \frac{1}{2}|11\rangle$$

- ▶ The amplitude of the $|00\rangle$ state is $\frac{1}{2}$

- ▶ The probability of measuring $|\psi\rangle$ and obtaining $|00\rangle$ is $|\frac{1}{2}|^2 = \frac{1}{4}$

- ▶ Consider the following state vector:

$$|\psi\rangle = \frac{-1}{2}|00\rangle + \frac{1}{2}|01\rangle + \frac{1}{2}|10\rangle + \frac{1}{2}|11\rangle$$

- ▶ The amplitude of the $|00\rangle$ state is $\frac{-1}{2}$

- ▶ The probability of measuring $|\psi\rangle$ and obtaining $|00\rangle$ is $|\frac{-1}{2}|^2 = \frac{1}{4}$

Define Multiple Gate Result Through Matrix Multiplication

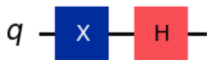


Figure 1: One Qubit Circuit with Two Gates

- ▶ Expected Output?
- ▶ Now show it one gate at a time.
- ▶ Now show it with a combination gate

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Overlap of Wavefunctions

- ▶ For an inner product where one of the states is a statevector and the other state is a basis state, the calculation is called an overlap
 - ▶ It determines the portion of the statevector in the direction of the basis vector
- ▶ Example: Consider the following basis in Cartesian coordinates

$$|x\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad |y\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad |\phi\rangle = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

- ▶ Then $\langle y|\phi\rangle = 4$ which is the overlap between $|y\rangle$ and $|\phi\rangle$

Outer Product

- ▶ An outer product takes two vectors and creates a matrix (an inner product takes two vectors and creates a scalar).
- ▶ Consider the following two vectors of length 3:

$$|x\rangle = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} \quad |y\rangle = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

- ▶ The outer product between these two vectors, represented as $|x\rangle\langle y|$ is

$$|x\rangle\langle y| = \begin{bmatrix} x_0 y_0^* & x_0 y_1^* & x_0 y_2^* \\ x_1 y_0^* & x_1 y_1^* & x_1 y_2^* \\ x_2 y_0^* & x_2 y_1^* & x_2 y_2^* \end{bmatrix}$$

Completeness Relation

► If the states $|x_i\rangle$ form a complete basis then:

$$\sum_i |x_i\rangle\langle x_i| = \mathbf{I}$$

Projection Operator

- ▶ A useful application of the outer product is in the construction of projection operators.
- ▶ The projection operator *projects* out a specific component of a of a state related to the basis state that was used to the projection operator.
- ▶ Example: Consider the following basis in Cartesian coordinates

$$|x\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad |y\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad |\phi\rangle = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

- ▶ $|y\rangle\langle y|$ is the projection operator for $|y\rangle$, so

$$|y\rangle\langle y|\phi\rangle = |y\rangle 4 = 4|y\rangle = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

Classical Linear Search

- ▶ If the data is sorted there are a variety of algorithms which have good performance
- ▶ If the data is unsorted you are left essentially with brute force
 - ▶ Average performance is $\frac{N}{2}$ searches
 - ▶ Worst case is N searches
- ▶ Computational Performance: $O(N)$

A New Way of Thinking of the Algorithm

- ▶ Standard algorithm returns the index of the wanted element
- ▶ Consider instead marking the indices corresponding to the wanted element

```
def linear_search_version_2 (my_list, element):
    length = len(my_list)
    results = np.zeros(length)
    for i in range(length):
        if my_list[i] == element:
            results[i] = 1
    return results
```

Reflections

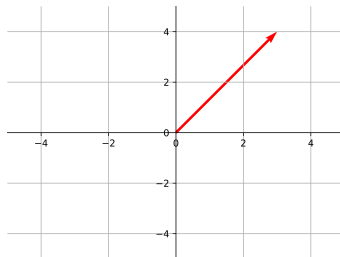


Figure 2: Reflection About the X Axis

Reflections

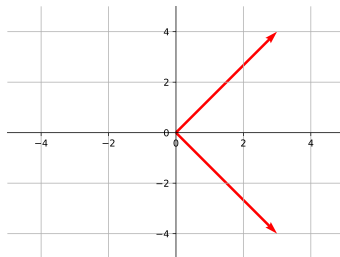


Figure 3: Reflection About the X Axis

Reflections

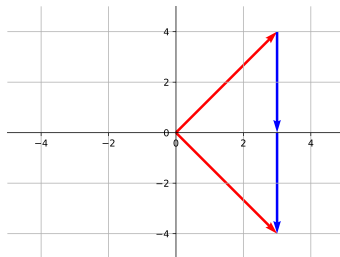


Figure 4: Reflection About the X Axis

Mathematical Representations of Reflections

$$\begin{bmatrix} 3 \\ 4 \end{bmatrix} - \begin{bmatrix} 0 \\ 4 \end{bmatrix} - \begin{bmatrix} 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 4 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

► But consider the following representation:

$$|x\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad |y\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad |\phi\rangle = 3|x\rangle + 4|y\rangle$$

Mathematical Representations of Reflections

- ▶ Then we can represent the reflection as:

$$\text{ref}_x(|\phi\rangle) = |\phi\rangle - 4|y\rangle - 4|y\rangle = |\phi\rangle - 2(4|y\rangle)$$

- ▶ But remember that from our discussion of overlaps, $\langle y|\phi\rangle = 4$, so

$$\text{ref}_x(|\phi\rangle) = |\phi\rangle - 2|y\rangle\langle y|\phi\rangle = (\mathbf{I} - 2|y\rangle\langle y|)|\phi\rangle$$

- ▶ Where we are reflecting around the x-axis, so y is the other axis

Mathematical Representations of Reflections

- For a reflection in more than two-dimensional space we would need to subtract the outer products of all other basis vectors besides the axis we are rotating around:

$$ref_x(|\phi\rangle) = (\mathbf{I} - 2|y\rangle\langle y| - 2|z\rangle\langle z|)|\phi\rangle$$

- This can be tedious for many basis vectors, but remember that the identity matrix can be represented as a sum of outer products of all basis vectors. So in 3D Cartesian:

$$\begin{aligned} ref_x(|\phi\rangle) &= (\mathbf{I} - 2|y\rangle\langle y| - 2|z\rangle\langle z|)|\phi\rangle \\ &= (|x\rangle\langle x| + |y\rangle\langle y| + |z\rangle\langle z| - 2|y\rangle\langle y| - 2|z\rangle\langle z|)|\phi\rangle \\ &= (|x\rangle\langle x| - |y\rangle\langle y| - |z\rangle\langle z|)|\phi\rangle \end{aligned}$$

Mathematical Representations of Reflections

- Now add and subtract by the outer product of the axis we are rotating around:

$$\begin{aligned}ref_x &= (|x\rangle\langle x| + |x\rangle\langle x| - |x\rangle\langle x| - |y\rangle\langle y| - |z\rangle\langle z|)|\phi\rangle \\&= (2|x\rangle\langle x| - (|x\rangle\langle x| + |y\rangle\langle y| + |z\rangle\langle z|)|\phi\rangle \\&= (2|x\rangle\langle x| - \mathbf{I})|\phi\rangle\end{aligned}$$

- Generalization: To rotate a statevector $|\phi\rangle$ around any axis k :

$$ref_k(|\phi\rangle) = (2|k\rangle\langle k| - \mathbf{I})|\phi\rangle$$

Parts of Grover's Algorithm

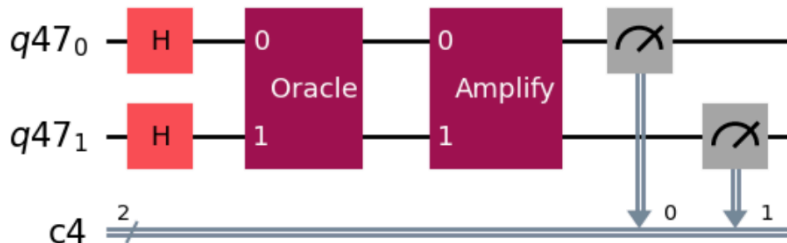


Figure 5: Grover's Algorithm

Hadamard Gates

- First step is to apply a Hadamard gate to every qubit, creating a superposition of every possible state

$$H^{\otimes n}|0^n\rangle = \frac{1}{\sqrt{N}} \sum_{x \in \{0,1\}^n} |x\rangle = |\phi\rangle$$

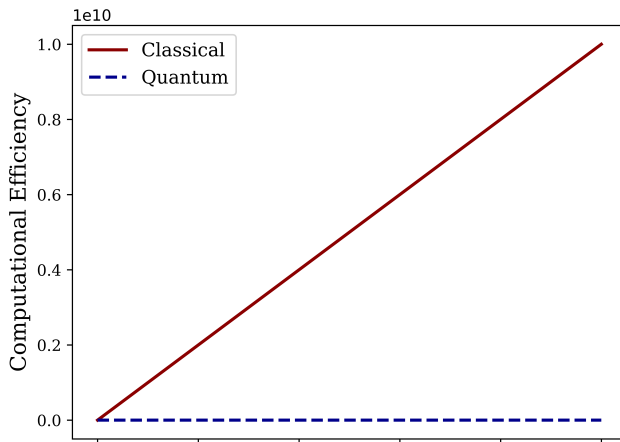
Oracle

- ▶ The goal of the algorithm is to flip the sign on the amplitude of the desired state(s)
 - ▶ Grover's can be used to find more than one desired solution at a time
- ▶ The oracle should flip the sign of the amplitude for all desired states but leave all other amplitudes unchanged

Amplification Algorithm (Diffusion Algorithm)

- ▶ A negative amplitude gives the same probability as a positive amplitude, so we need another step in the algorithm
- ▶ The amplification algorithm (amplitude amplification algorithm or diffusion algorithm) increase the amplitude on the marked states but decreases the amplitude on the unmarked states
- ▶ **NOTE** the oracle and amplification algorithm may have to be applied more than once to achieve significant separation in amplitudes between the marked and unmarked states.

$O(N)$ vs. $O(\sqrt{N})$ Run Times



Visual Walkthrough

- ▶ In the next few slides we will visually walkthrough what Grover's algorithm is doing as it processes a system.
- ▶ The basic steps are to negate the amplitude of the desired state (oracle) and then reflect the entire state around the mean amplitude (amplification)

Step 1: Starting Point for Two Qubits

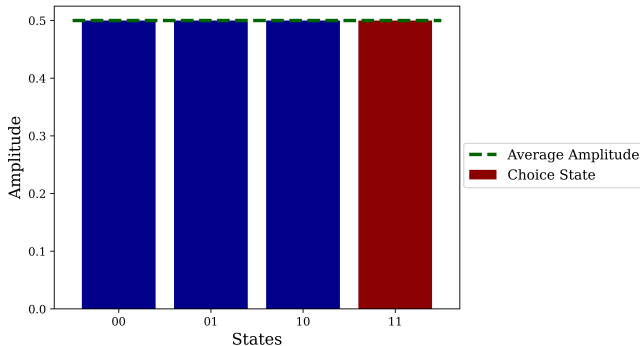


Figure 7: Grover's Algorithm Visualization Step 1

Step 2: Negate Amplitude of Desired State

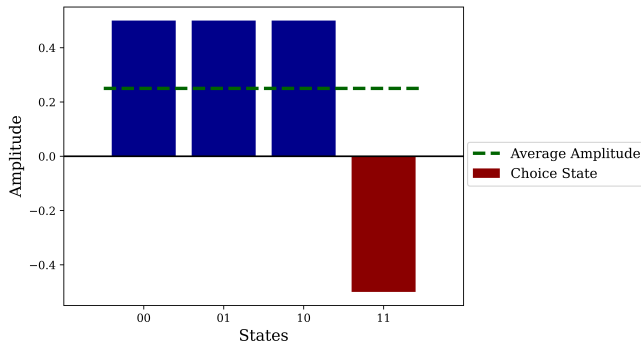


Figure 8: Grover's Algorithm Visualization Step 2

Step 3: Reflect Around Mean Amplitude

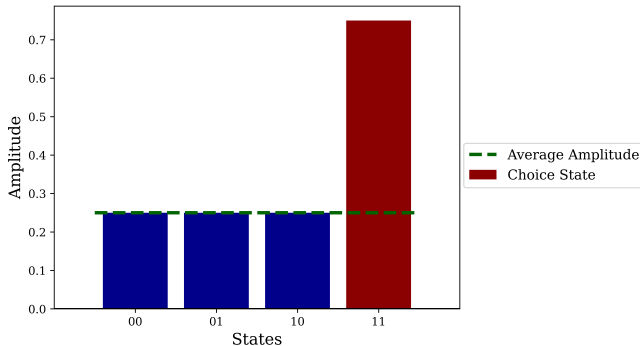


Figure 9: Grover's Algorithm Visualization Step 3

Step 4: Negate Amplitude of Desired State

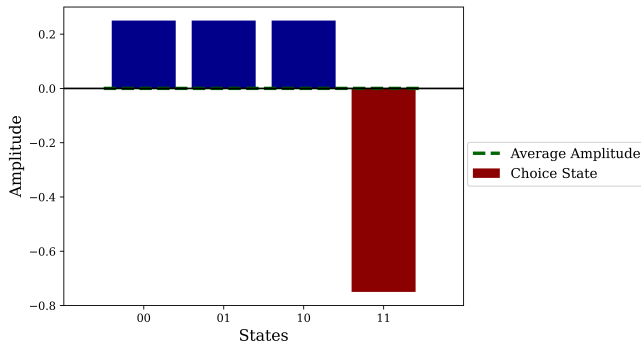


Figure 10: Grover's Algorithm Visualization Step 4

Step 5: Reflect Around Mean Amplitude

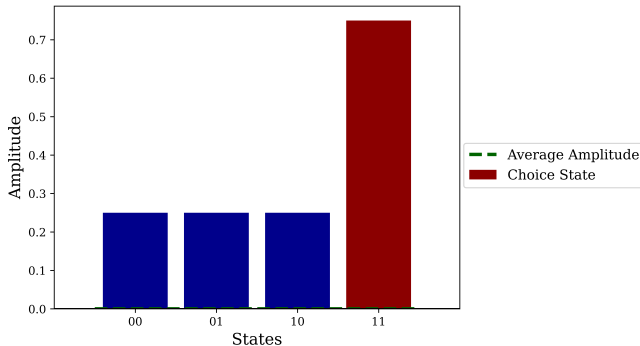
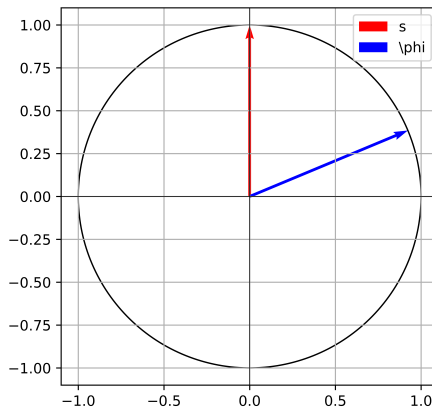
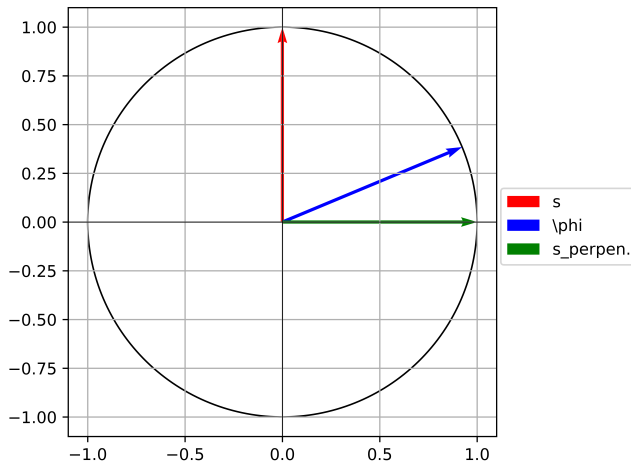


Figure 11: Grover's Algorithm Visualization Step 5

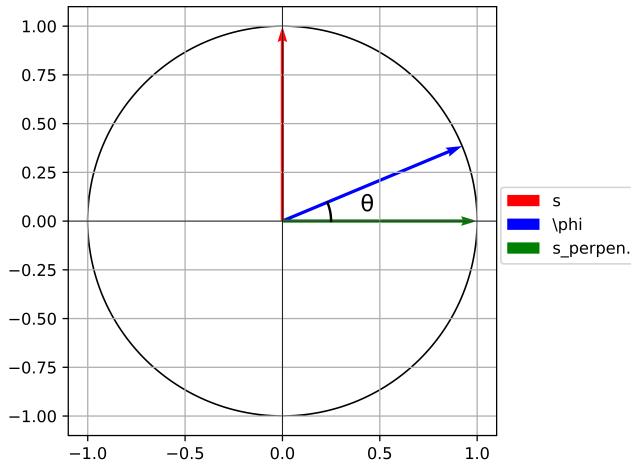
How Many Times To Run → Grover's Circle



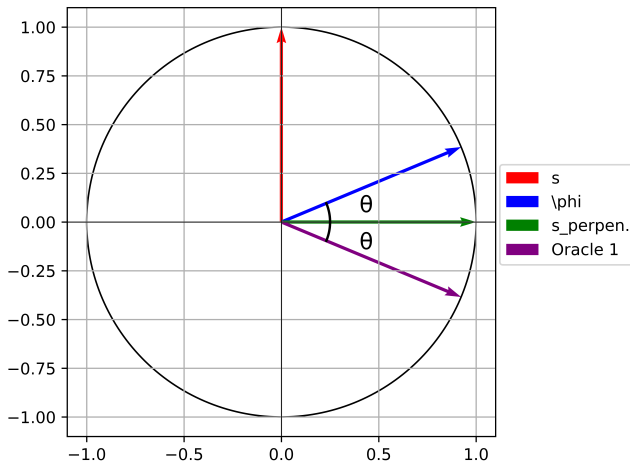
Add $|s^\perp\rangle$, a state which is perpendicular to $|s\rangle$



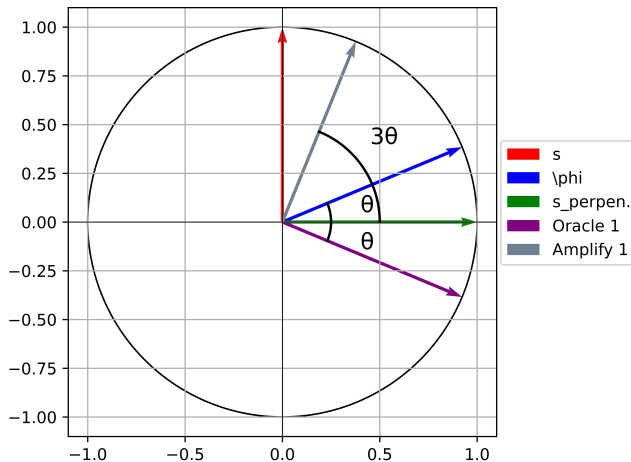
Note the angle θ



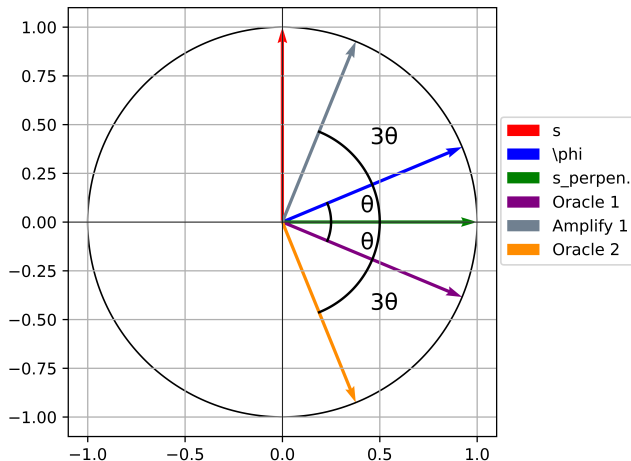
Negate the component of $|\phi\rangle$ that comes from $|s\rangle$ (Oracle)



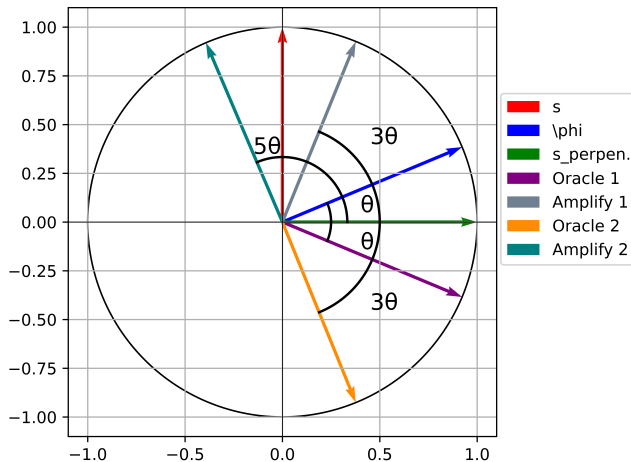
Reflect around the original value of $|\phi\rangle$ (Amplification)



Negate the component of $|\phi\rangle$ that comes from $|s\rangle$ (Oracle)



Reflect around the original value of $|\phi\rangle$ (Amplification)



How Many Times To Run → Grover's Circle

► Now some trigonometry

$$\sin\theta = \frac{1/\sqrt{N}}{1} \longrightarrow \langle s|\phi\rangle = \frac{1}{\sqrt{N}}, \quad |\langle\phi|\phi\rangle|^2 = 1$$

$$\theta = \arcsin\left(\frac{1}{\sqrt{N}}\right) \approx \frac{1}{\sqrt{N}}$$

$$(2t+1)\theta = \frac{\pi}{2} \longrightarrow t = \frac{\pi}{4}\sqrt{N} - \frac{1}{2}$$

How Many Times To Run → Grover's Circle

- ▶ In general the algorithm will run $\frac{\pi}{4} \sqrt{\frac{N}{M}}$ times where there are N items in the search space and the algorithm is looking for M different items.
 - ▶ Typically this equation is “floored” to avoid overshooting

What Could the Amplification Be?

$$U_d = 2|\phi\rangle\langle\phi| - \mathbf{I}$$

- ▶ Remember this step is a rotation around the mean amplitude
- ▶ But since $|\phi\rangle$ is a superposition of all possible states:

$$H^{\otimes n}(2|0\rangle\langle 0| - \mathbf{I})H^{\otimes n}$$

- ▶ Very similar implementation as the Oracle, same gates will be involved

Amplification Algorithm

1. Hadamard to all qubits
2. NOT to all qubits
3. Multi-controlled-Z where all top qubits are the control and the bottom qubit is the target
4. NOT to all qubits
5. Hadamard to all qubits

